

# Power Hardware In the Loop Study of Hybrid Energy Storage System in DC Microgrids

## Introduction

- ❖ In Power hardware in the loop (PHIL), one part of the system is numerically simulated in OPAL-RT and other part is the actual hardware under test.
- ❖ The OPAL-RT and hardware under test are interfaced together using a power amplifier.
- ❖ The PHIL is an excellent way to validate the performance of the system as the effect of the physical hardware in the system can be monitored in real time.

## System Architecture and Operation

- ❖ The power amplifier is used to interface between the OPAL-RT and hardware under test.
- ❖ The lithium ion battery with bi-directional DC-DC converter are considered as hardware under test.
- ❖ The DC microgrid with PV system, SC system and DC load is simulated in OPAL-RT system.
- ❖ The voltage reference from the OPAL-RT simulation is sent to the power amplifier through an optical fiber link.
- ❖ The power amplifier emulates the DC link voltage.
- ❖ The power is exchanged between the power amplifier and battery system based on the DC link voltage output from power amplifier.
- ❖ The current measurement from the battery system is feedback to the OPAL-RT system and the simulation is updated in real-time.

## Advantages of PHIL Study

- ❖ Shorter setup time.
- ❖ Lower development cost.
- ❖ Easier to reconfigure for rapid prototyping.

## System Parameter for PHIL Study

Category	Values
<b>PV Specifications</b>	
Open circuit voltage	320V
Short circuit voltage	40 A
<b>Battery specifications</b>	
Nominal voltage	260
Rated energy	10kWh
<b>SC specifications</b>	
Terminal voltage	300V
Capacitance	5.8F
<b>PA specifications</b>	
Power capacity	45kVA
Peak current	616A
Maximum DC output voltage	424V
<b>Converters Parameters</b>	$L_p = 2 \text{ mH}, L_{bat} = 6.3 \text{ mH}, L_{scap} = 5 \text{ mH}, R_L = 200 \Omega, C_b = 2200 \mu\text{F}, C_{pv} = C_s = 500 \mu\text{F}$
<b>Controller Parameters</b>	$K_{p,pv} = 0.1, k_{i,pv} = 1$ $K_{p,b} = 0.1, k_{i,b} = 1$ $k_{p,sc} = 0.4, k_{i,sc} = 150$ $k_{p,v} = 1, k_{i,v} = 10$
<b>Reference values</b>	$V_{ref} = 400 \text{ V}, f_{sw} = 10 \text{ kHz}$ LPF cut-off freq = $2\pi \cdot 5 \text{ rad/s}$ $T_s = 25 \mu\text{s}$ (OPAL-RT simulation) $T_s = 20 \mu\text{s}$ (dSPACE 1103 controller)

## Experiment setup and Results

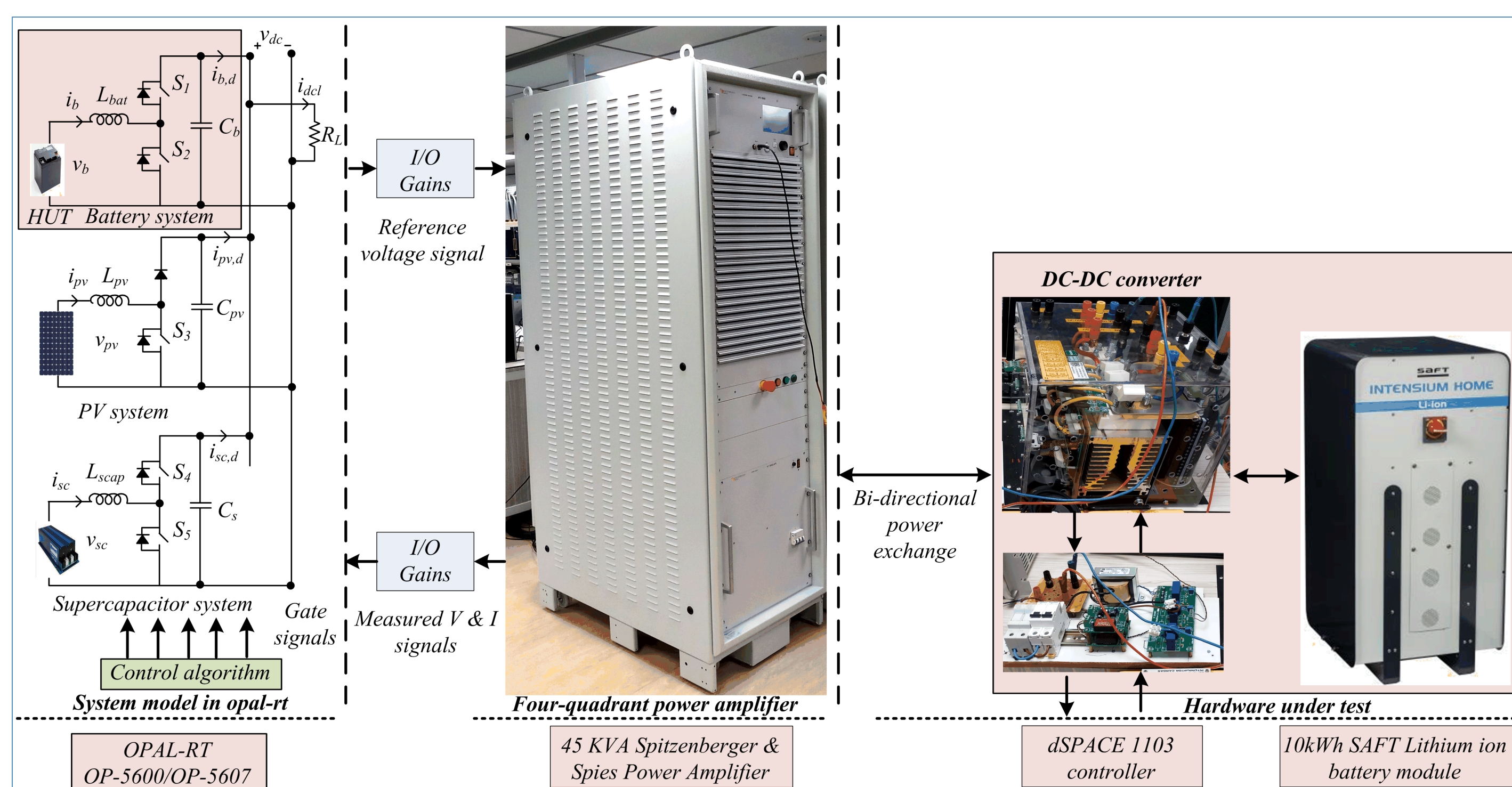


Figure 1: Experiment setup for PHIL study.

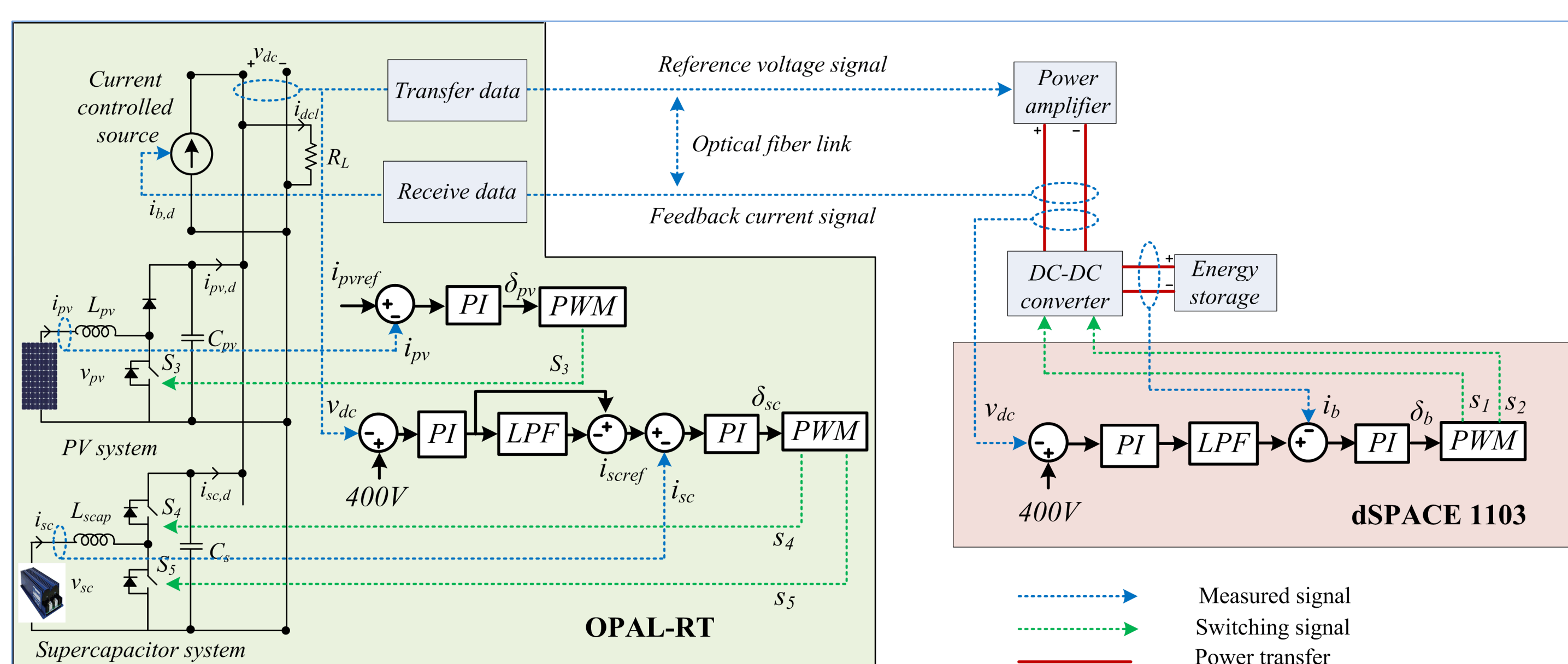


Figure 2: Closed loop system architecture for PHIL study.

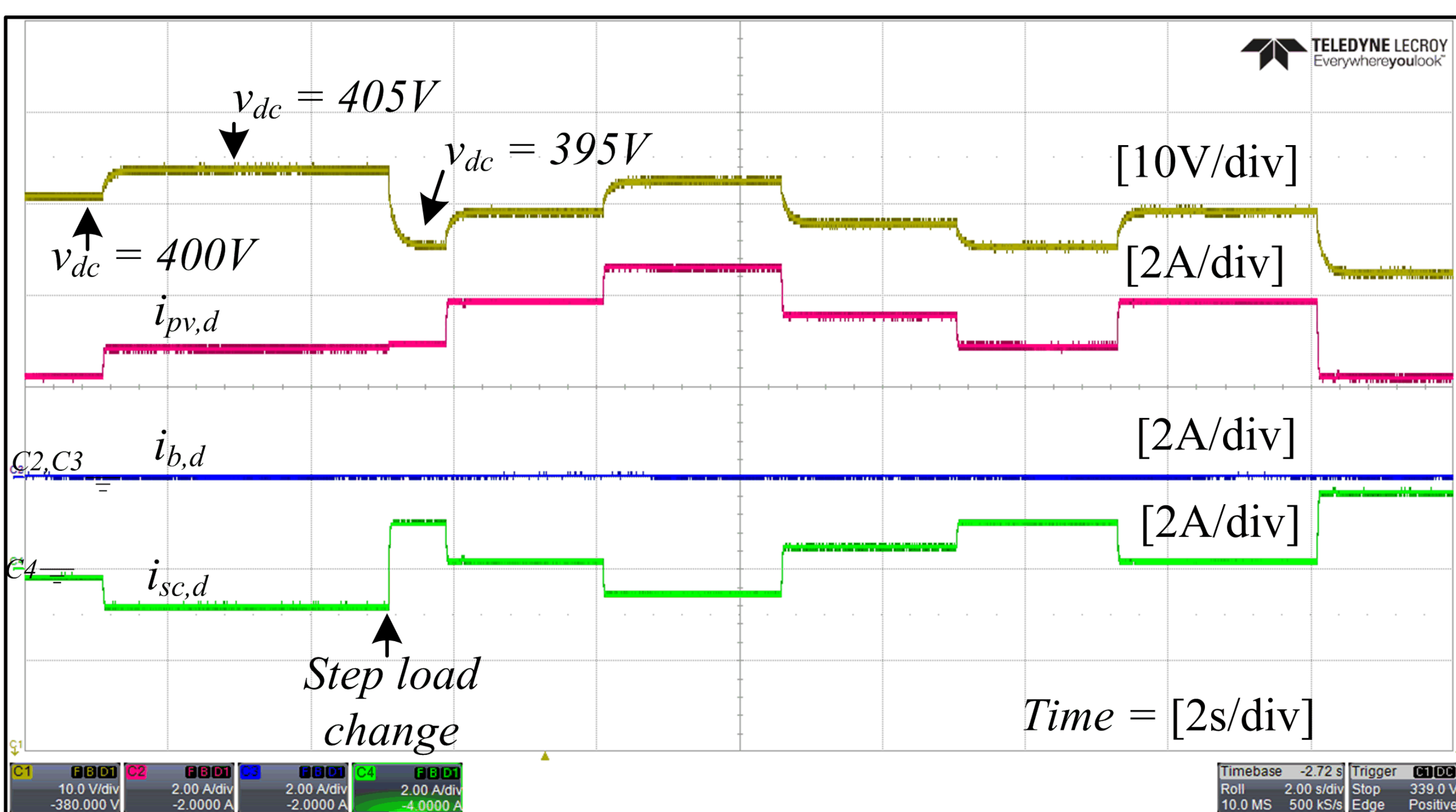


Figure 3: PHIL experiment results without battery system

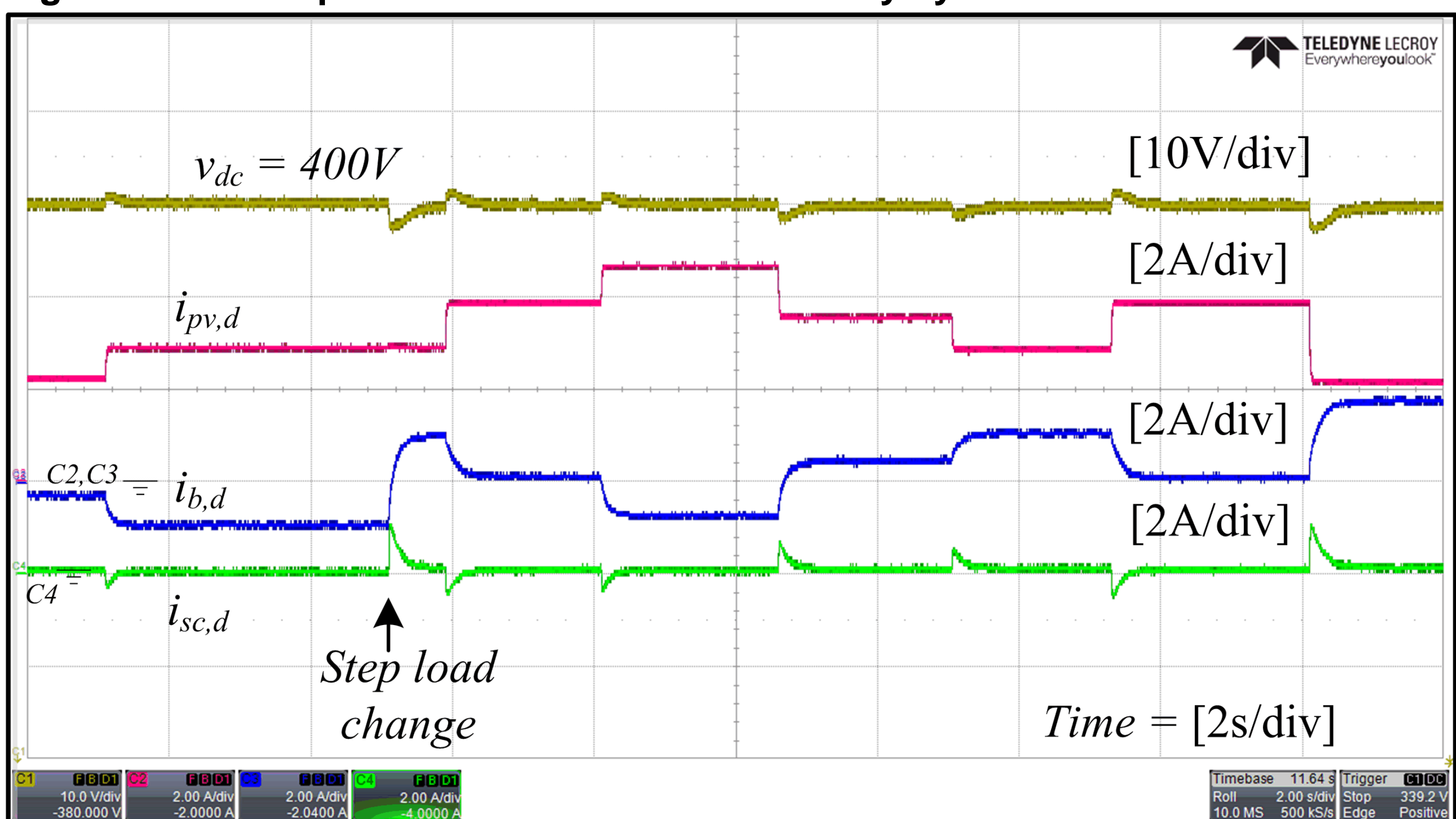


Figure 4: PHIL experiment results with battery system

## Conclusion

- ❖ The closed loop operation is achieved such that the DC link voltage is well maintained at  $v_{dc} = 400V$  in spite of the DC load change and the PV current variations with battery system.
- ❖ The voltage deviation during the step load change is 2V, and the voltage is restored to its reference value in less than 400ms with the battery system.
- ❖ The presented PHIL experiment is effective for testing the energy storage devices for high power applications where the actual DC microgrid is not available.

## Principal Investigator

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